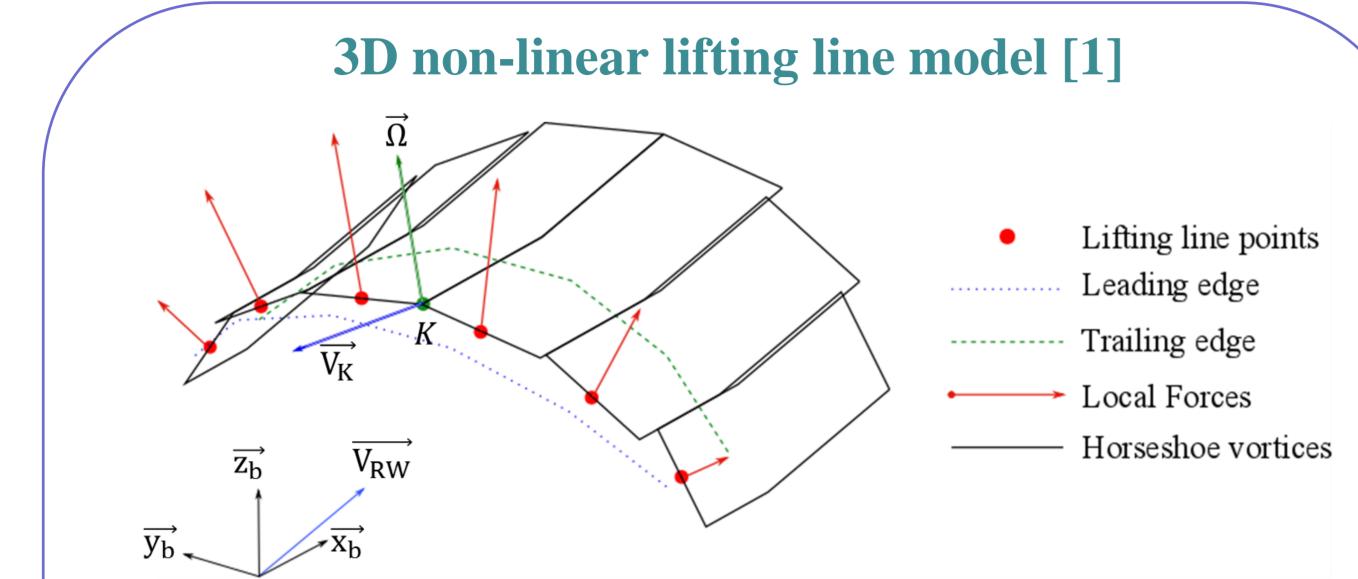


Kite as a Beam Modelling Approach: Assessment by Finite **Element Analysis**

<u>C. Duport</u>, A. Maison, A. Nême, J.-B. Leroux, K. Roncin, C. Jochum, Y. Parlier



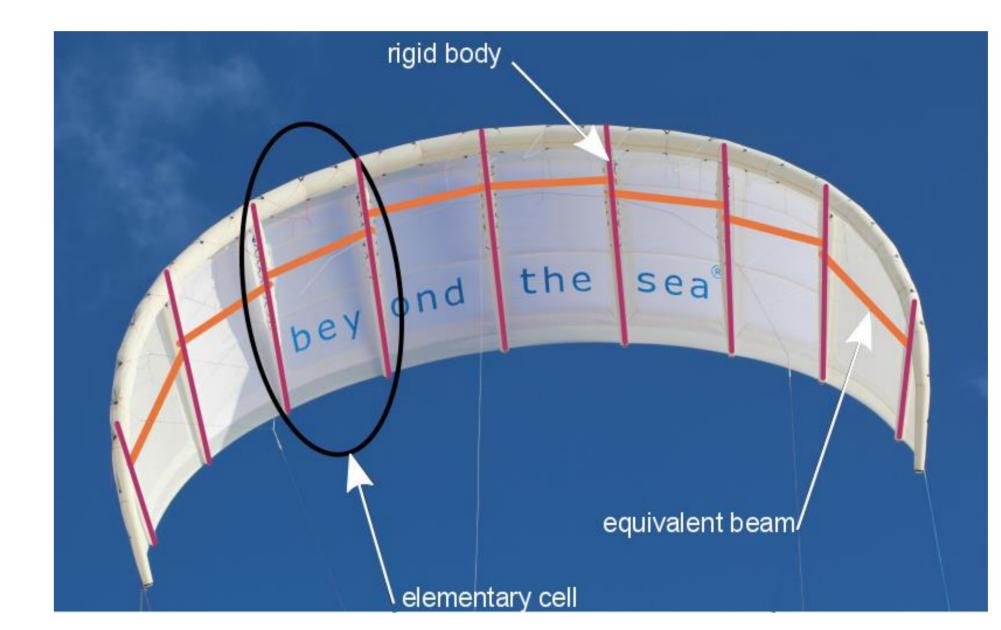
Kite as a Beam model [2]

- Kite considered as an assembly of elementary cells \bullet
- Cell composed of:
 - Portion of the inflatable leading edge: modelled as a beam
 - Two half inflatable battens: modelled as beams
 - Corresponding canopy: modelled as a shell
- Each elementary cell is replaced by an equivalent beam



Example of a low discretised lifting line model

- Prandtl lifting line theory adapted to wings with variable dihedral and sweep angles. Finite wing and its wake represented by a set of horseshoe vortices of different strengths Γ
- Inclusion of the non-linearity of the lift coefficient •
- Iterative solution:
 - Computation of the induced velocities with the Biot-Savart law
 - Computation of the circulation from the equivalence between local lift calculated from the Kutta formula and from the polar of the section



Comparison of the 3D non-linear lifting line method with 3D RANSE results (Star-CCM+®) [3]

of

1.2

0.2

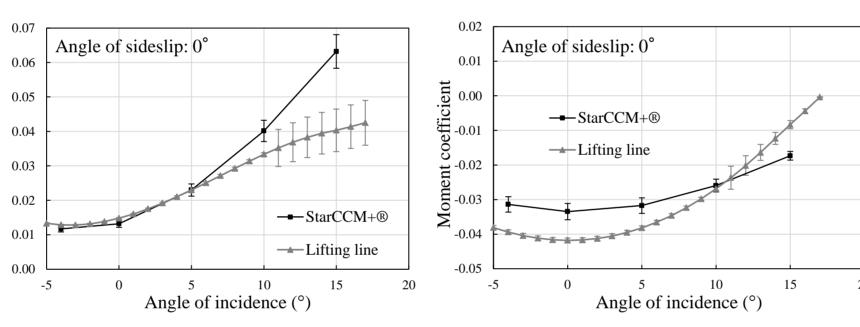
-1.0

-0.5

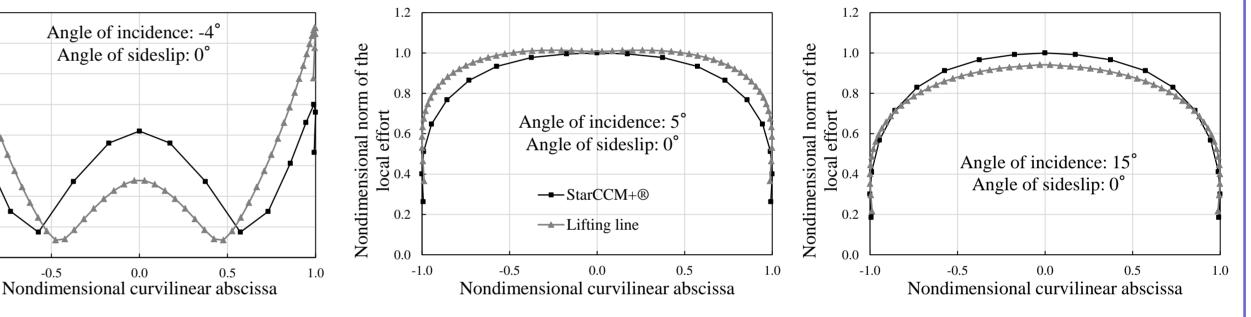
0.0

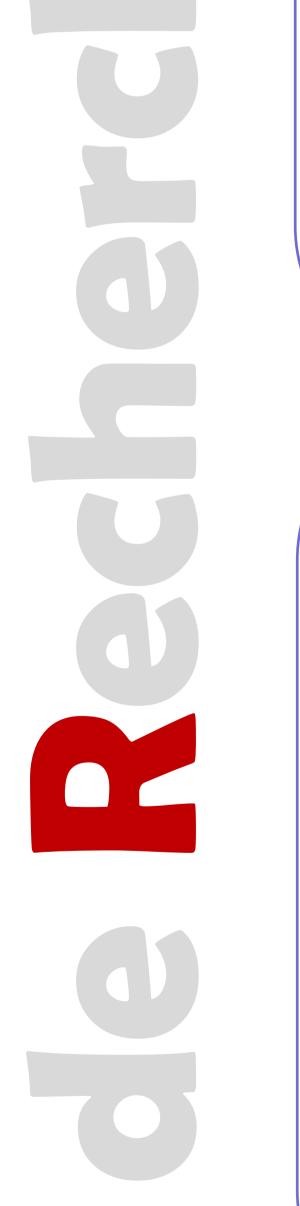
8.0 GL al

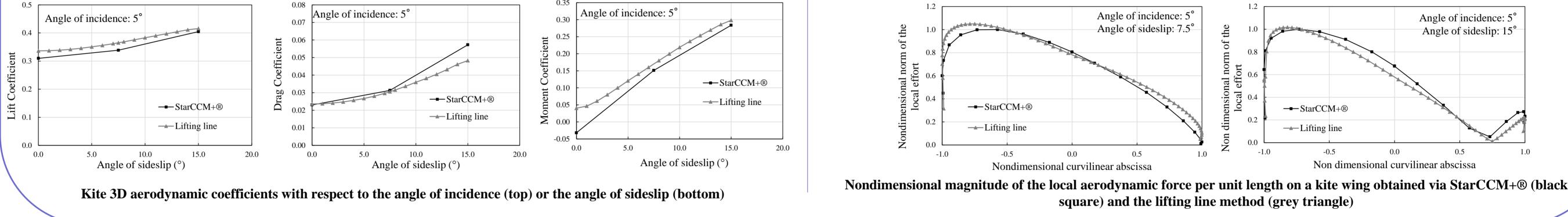
- Semi-circular kite of radius 1.0*m* with a NACA2412 section Non-linear swept law •
- Angle of sideslip: 0° 0.6 $\overset{\mathrm{O}}{\mathrm{O}}$ 0.2 Lift Ä Lifting line Angle of incidence (°)



- Linear twist law, from 0° at root to 5° at tips • Non-linear chord law from 1.0*m* at root to 0.1*m* at tips
- Computation time:
 - Lifting line: 0.5*s* with a standard PC
 - StarCCM+[®]: 40*min* with 8 cores

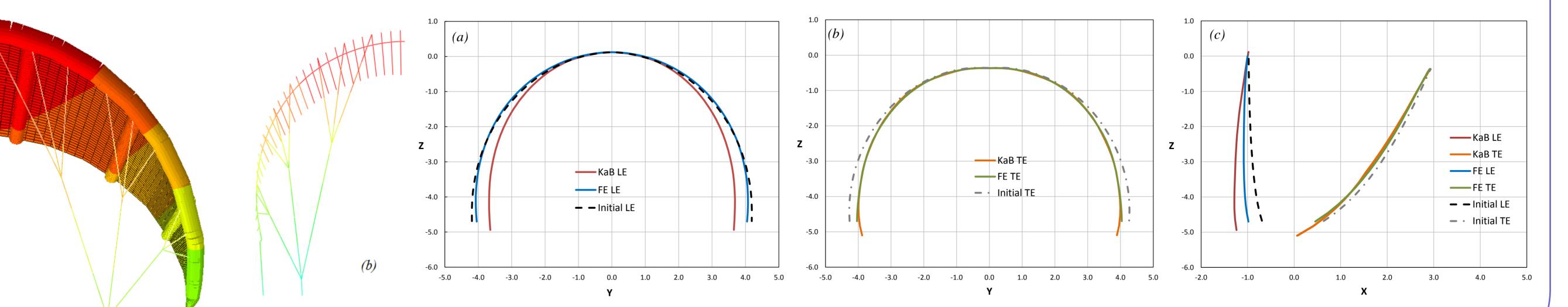






Comparison of the Kite as a Beam model with a Finite Element model [4]

- Fluid-Structure Interaction (FSI) on a $50m^2$ kite at 10° of incidence with an • apparent wind of 25m/s and 75m of tether length. The anchor point of the tethers is a fixed point and the tethers and bridles system are represented by truss elements.
 - Comparison between the Kite as a Beam model coupled with the 3D non-linear lifting line method and the Finite Element model coupled with a linear lifting line. The results of the two lifting line are slightly different.
 - Computation time: few minutes for the KaB FSI, few hours for the FE FSI



 (a) Complex Finite Element model with shell and beam elements, (b) Kite as a beam model. The color scale represents the displacement magnitude

(a) Front view of the leading edge (LE) of the kite, undeformed (initial), after convergence with the Kite as a Beam model (KaB), after convergence with the Finite Element model (FE). (b) Front view of the trailing edge (TE) of the kite, undeformed and after convergence with the Kite as a Beam model and the Finite Element model. (c) Side view of the leading and trailing edge of the kite, undeformed and after convergence of the two models.

Acknowledgements :

The authors are grateful to the French agency for energy development and control (ADEME) for the funding of this study.

References:

(a)

[1] Duport C., Leroux J.-B., Roncin K., Jochum C., Parlier Y.: Comparison of 3D non-linear lifting line method calculations with 3D RANSE simulations and application to the prediction of the global loading on a cornering kite. In: Proceedings of the 15th Journées de l'Hydrodynamique, Brest, France, 22-24 Nov 2016.

[2] Solminihac A., Nême A., Duport C., Leroux J.-B., Roncin K., Jochum C., Parlier Y.: Kite as a Beam: A Fast Method to get the Flying Shape. In: Schmehl, R (eds) Airborne Wind Energy, Green Energy and Technology, Chap. 4, pp. 77-95. Springer (2018).

[3] Duport C., Deberque M., Leroux J.-B., Roncin K., Jochum C.: Local results verification of a 3D non-linear lifting line method for Fluid-Structure interaction simulation on a towing kite for vessels. In: Proceedings of the 11th Symposium on High-Performance Marine Vehicles, Zevenwacht, South Africa, 11-13 Sep 2017.

[4] Maison A., Nême A., Leroux J.-B.: De la problématique du dimensionnement de grands kites. In: ATMA 2017



